

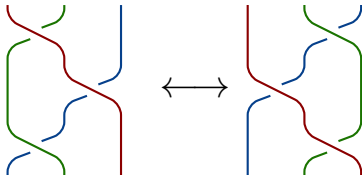
Structure groups of YBE solutions: cohomological applications

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$$(ab)c = a(bc)$$

3		
2	6	6
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$$z^{-1}(y^{-1}xy)z = (z^{-1}y^{-1}z)(z^{-1}xz)(z^{-1}yz)$$

1

Yang-Baxter equation

Data:

- monoidal category \mathcal{C} ($= \mathbf{Vect}_{\mathbb{k}}$);
- object S ;
- morphism $r: S \otimes S \rightarrow S \otimes S$.

braiding

YBE:

$$r_1 r_2 r_1 = r_2 r_1 r_2: S^{\otimes 3} \rightarrow S^{\otimes 3}$$

$$r_1 = r \otimes \text{Id}_S, r_2 = \text{Id}_S \otimes r$$

Topological avatar:

$$r \leftrightarrow \text{crossing}$$



YBE \leftrightarrow



$$\text{crossing} = \text{crossing}$$

Reidemeister III
move


2

YBE zoology

We'll mostly work with **set-theoretic** solutions: $C = \mathbf{Set}$ (Drinfel'd '90).

linearise deform
  linear solutions.

Example: $r(x, y) = (y, x)$

 R-matrices;

 $r_{\text{Lie}}(x \otimes y) = y \otimes x + \hbar 1 \otimes [x, y]:$

YBE for r_{Lie} \iff Jacobi for $[\]$
 1 central

Example: $r_{\text{SD}}(x, y) = (y, x \triangleleft y):$

YBE for r_{SD} \iff self-distributivity for \triangleleft

Self-distributivity: $(x \triangleleft y) \triangleleft z = (x \triangleleft z) \triangleleft (y \triangleleft z)$

Example: $r_{SD}(x, y) = (y, x \triangleleft y)$:

YBE for $r_{SD} \iff$ self-distributivity for \triangleleft

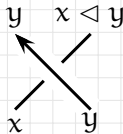
Self-distributivity: $(x \triangleleft y) \triangleleft z = (x \triangleleft z) \triangleleft (y \triangleleft z)$

Examples:

- group S with $x \triangleleft y = y^{-1}xy$:
- abelian group S , $t: S \rightarrow S$, $a \triangleleft b = ta + (1-t)b$.

Applications:

- invariants of knots and knotted surfaces (Joyce & Matveev '82);



- Hopf algebra classification (Andruskiewitsch–Graña '03).

Example: Involutive solutions r , i.e., $r^2 = \text{Id}_{S \times S}$.

A solution $r(a, b) = (\sigma_a(b), \tau_b(a))$ is called **left non-degenerate (LND)** if the maps τ_b are bijective.

Theorem (*Rump '04*): LND involutive solutions $\xleftrightarrow{1:1}$ **cycle sets**.

Theorem (*Soloviev & Lu-Yan-Zhu '00, L.-Vendramin '17*):

- LND solution $(S, r) \rightsquigarrow$ SD operation \triangleleft_r on S ;
- \triangleleft_r captures major properties of r ; for instance,

$$r^2 = \text{Id}_{S \times S} \iff a \triangleleft_r b = a.$$

So, involutive and self-distributive solutions can be seen as two perpendicular axes in the space of all LND solutions. Schematically,

$$"0 \rightarrow \mathbf{CycleSets} \rightarrow \mathbf{LNDSol} \rightarrow \mathbf{SD} \rightarrow 0"$$

Getting more exotic

We will tolerate **non-invertible** solutions.

Example: **free self-distributive structures.**

Application: **total order on braid groups** (*Dehornoy '91*).

Even worse: some of our solutions are **idempotent**: $rr = r$.

Examples: ✓ **Monoid** $(S, \cdot, 1)$, $r_{A_{SS}}(x, y) = (1, x \cdot y)$:

YBE for $r_{A_{SS}}$ \iff associativity for \cdot
 1 unit

✓ **Factorised monoid** $G = HK$,

$$S = H \cup K, \quad r_{\text{Fact}}(x, y) = ((xy)_H, (xy)_K).$$

✓ **Lattice** (S, \wedge, \vee) , $r_L(x, y) = (x \wedge y, x \vee y)$.

So, YBE provides a **unifying framework** for many algebraic situations.

Question: Can anything non-trivial be done in such a general setting?

Answer: Yes!

- 1) A study of **structure groups** of solutions.
- 2) A **(co)homology theory**.

Structure group, or universal enveloping group of (S, r) :

$$G(S, r) = \langle S \mid xy = y'x' \text{ whenever } r(x, y) = (y', x') \rangle$$

Structure monoids and algebras are defined similarly.

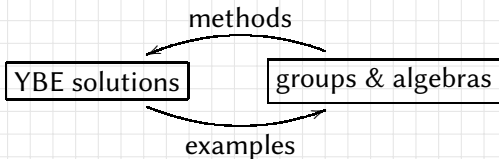
$$G(S, r, e) := G(S, r) / e = 1$$

Examples:

- ✓ Factorised monoid $G = HK$, $r_{\text{Fact}}(x, y) = ((xy)_H, (xy)_K)$:
 $\text{Mon}(H \cup K, r_{\text{Fact}}, 1_G) \simeq G$.
- ✓ Lie algebra V , $V' = V \oplus \mathbb{k}1$, 1 central, $r_{\text{Lie}}(x \otimes y) = y \otimes x + 1 \otimes [x, y]$:
 $\text{Alg}(V', r_{\text{Lie}}, 1) \simeq \text{UEA}(V, [])$.

Why should a group theorist care about YBE?

$$G(S, r) = \langle S \mid xy = y'x' \text{ whenever } r(x, y) = (y', x') \rangle$$



Strategy (Cedó–Jespers–del Río '10):

Step 1: classify all structure groups G (or certain quotients thereof);

Step 2: classify all YBE solutions with $G(S, r) \cong G$.

Theorem: $r^2 = \text{Id} \implies$

- ✓ $\text{Mon}(S, r)$ is of I-type, cancellative, Ore;
- ✓ $\text{Grp}(S, r)$ is solvable, Garside, Bieberbach;
- ✓ $\mathbb{k} \text{Mon}(S, r)$ is Koszul, noetherian, Cohen–Macaulay,
Artin–Schelter regular

(Manin, Gateva-Ivanova & Van den Bergh, Etingof–Schedler–Soloviev, Jespers–Okniński, Chouraqui 80'-...).

Construction (Fenn et al. '93, Carter et al. '04, L. '13):

✓ $C^n := \text{Maps}(S^{\times n}, \mathbb{Z}_m)$;

✓ $d^n: C^n \rightarrow C^{n+1}$,

$$d^n = \sum_{i=1}^{n+1} (-1)^{i-1} (d_l^{n;i} - d_r^{n;i}).$$

Versions:

✓ diagrammatic:

$$f(x'_1 \dots x'_{i-1} x_{i+1} \dots x_{n+1})$$

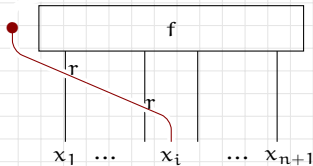
$$\uparrow$$

$$x'_i x'_1 \dots x'_{i-1} x_{i+1} \dots x_{n+1}$$

$$r_1 \dots r_{i-1} \uparrow$$

$$x_1 \dots x_{n+1}$$

$$d_l^{n;i} f =$$



✓ a topological realisation;

✓ using **quantum shuffles**;

✓ using a differential graded bialgebra (Farinati–García-Galofre '16).

Why I like braided cohomology

- ① Describes **diagonal deformations** (Freyd–Yetter '89, Eisermann '05):

$$r_\omega(x, y) = q^{\omega(x, y)} r(x, y), \quad \omega: S \times S \rightarrow \mathbb{Z}_m.$$

$$d^2\omega = 0 \quad \implies \quad r_\omega \text{ is a YBE solution.}$$

- ② Yields **knot and knotted surface invariants** (Carter et al. '01):

$$(S, r)\text{-coloured diagram } (D, \mathcal{C}) \quad \& \quad \omega: S \times S \rightarrow \mathbb{Z}_m$$

$$\rightsquigarrow \text{ Boltzmann weight } \mathcal{B}_\omega(\mathcal{C}) = \sum_{\substack{y' \nearrow x' \\ x \searrow y}} \omega(x, y) - \sum_{\substack{x \nearrow y \\ y' \searrow x'}} \omega(x, y).$$

$$d^2\omega = 0 \quad \implies \quad \sum_{\mathcal{C}} t^{\mathcal{B}_\omega(\mathcal{C})} \text{ is a knot invariant;}$$

$$\omega - \omega' = d^1\psi \quad \implies \quad \omega \text{ and } \omega' \text{ yield equivalent invariants.}$$

③ Unifies cohomology theories for

✓ self-distributive structures

$$r_{SD}(x, y) = (y, x \triangleleft y)$$

✓ associative structures

$$r_{Ass}(x, y) = (1, x \cdot y)$$

✓ Lie algebras

$$r_{Lie}(x \otimes y) = y \otimes x + \hbar 1 \otimes [x, y]$$

.....

+ explains parallels between them,

+ suggests theories for new structures:

Example: cycle sets and braces (L.-Vendramin '17).

④ Computes the cohomology of structure groups.

Quantum symmetriser \mathcal{QS} :

braided cohomology

$$H^*(S, \mathbb{Z}_m)$$

cup product \smile

small complexes

$$\xleftarrow{\mathcal{QS}}$$

Hochschild cohomology

$$HH^*(\text{Mon}(S, r), \mathbb{Z}_m)$$

cup product \smile

tools

Theorem: \mathcal{QS} is an **isomorphism** when

- ✓ $rr = \text{Id}$ (Farinati–García-Galofre '16);
- ✓ $rr = r$ (L. '17).

Open question: For general r ?

Applications:

- ✓ Spectral sequence for factorised monoids $G = \text{HK}$.
- ✓ Cohomology computations for **plactic monoids**.