

INVERSE SEMI-BRACES AND THE YANG-BAXTER EQUATION

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Algebra Days in Caen 2022: from Yang–Baxter to Garside, March 24-25 2022



Introduction

In the '90s, Drinfel'd [3] raised the still open issue of finding and classifying all set-theoretical solutions of the Yang-Baxter equation, a fundamental equation of statistical mechanics. If S is a set, a map $r : S \times S \rightarrow S \times S$ is said to be a *set theoretical solution of the Yang-Baxter equation*, shortly a *solution*, if the relation

$$(r \times \text{id}_S)(\text{id}_S \times r)(r \times \text{id}_S) = (\text{id}_S \times r)(r \times \text{id}_S)(\text{id}_S \times r)$$

is satisfied. The algebraic structure of *brace* introduced by Rump [5] in 2007 as generalization of Jacobson radical ring is a tool to find solutions. In particular, any brace gives rise to an involutive solution r , i.e., $r^2 = \text{id}$. In this way, Rump traced a novel research direction and later fruitful results on this kind of solutions appeared.

Recently, we introduced the *inverse semi-braces* [2], more general structures than braces, that allow obtaining solutions that are not necessarily bijective.

Inverse semi-braces

We recall that a semigroup S is said to be an *inverse semigroup* if, for each $x \in S$, there exists a unique $x^{-1} \in S$ satisfying $xx^{-1}x = x$ and $x^{-1}xx^{-1} = x^{-1}$. In particular, xx^{-1} and $x^{-1}x$ are idempotents.

Definition. Let S be a set endowed of two operations $+$ and \cdot such that $(S, +)$ is a semigroup (not necessarily commutative) and (S, \cdot) is an inverse semigroup. Then, $(S, +, \cdot)$ is an *inverse semi-brace* if

$$a(b+c) = ab + a(a^{-1}+c) \quad (1)$$

holds, for all $a, b, c \in S$.

Semi-braces [1, 4] are instances of inverse semi-braces with (S, \cdot) a group. In addition, if $(S, +)$ is an abelian group, then the semi-brace S is a brace.

Example 1. Every inverse semigroup (S, \cdot) having central idempotents gives rise to two inverse semi-braces, setting $a+b = ab$ or $a+b = ba$, for all $a, b \in S$.

Example 2. If (S, \cdot) is an inverse semigroup and $(S, +)$ is a right zero semigroup (or a left zero semigroup), then S is an inverse semi-brace.

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Solutions associated to inverse semi-braces

Let S be an inverse semi-brace, $\lambda : S \rightarrow \text{End}(S, +)$, $a \mapsto \lambda_a$ and $\rho : S \rightarrow S^S$, $b \mapsto \rho_b$ the maps respectively defined by

$$\lambda_a(b) = a(a^{-1}+b) \quad \rho_b(a) = (a^{-1}+b)^{-1}b,$$

for all $a, b \in S$. Then, we call the map $r_S : S \times S \rightarrow S \times S$ given by

$$r_S(a, b) = (\lambda_a(b), \rho_b(a)),$$

for all $a, b \in S$, the *map associated to the inverse semi-brace* S .

The following are sufficient conditions to obtain solutions through inverse semi-braces.

Theorem 1 Let S be an inverse semi-brace and r_S the map associated to S . If the following conditions are satisfied

1. $(a+b)(a+b)^{-1}(a+bc) = a+bc$
2. $\lambda_a(b)^{-1} + \lambda_{\rho_b(a)}(c) = \lambda_a(b)^{-1} + \lambda_{(a^{-1}+b)^{-1}}\lambda_b(c)$
3. $\rho_b(a)^{-1} + c = (b^{-1}+c)(\rho_{\lambda_b(c)}(a)^{-1} + \rho_c(b))$, for all $a, b, c \in S$, then the map r_S is a solution.

In general, solutions associated to inverse semi-braces are not bijective.

The previous examples of inverse semi-braces satisfy the conditions of Theorem 1.

Examples

1 The map r_S associated to S in Example 2 with $a+b = ab$ and the map t_S associated to S with $a+b = ba$ are respectively given by

$$r_S(a, b) = (aa^{-1}b, b^{-1}ab) \quad t_S(a, b) = (aba^{-1}, abb^{-1}),$$

and are solutions.

2 The map r_S associated to S in Example 1 with $(S, +)$ a right zero semigroup is given by

$$r_S(a, b) = (ab, b^{-1}b)$$

and is an idempotent solution. Similarly, if $(S, +)$ a left zero semigroup, we get the idempotent solution

$$r_S(a, b) = (aa^{-1}, ab).$$

Note that if $|S| > 1$ such solutions are not isomorphic. In addition, it is clear that the number of inverse semigroups determines a lower bound for idempotent solutions.

The double semidirect product of inverse semi-braces

Theorem 2 Let S and T be two inverse semi-braces, $\sigma : T \rightarrow \text{Aut}(S)$ a homomorphism from (T, \cdot) into the automorphism group of the inverse semi-brace S , and $\delta : S \rightarrow \text{End}(T)$ an anti-homomorphism from $(S, +)$ into the endomorphism semigroup of $(T, +)$. Set ${}^u a := \sigma(u)(a)$ and $u^a := \delta(a)(u)$, for all $a \in S$ and $u \in T$, if it holds

$$(uv)^{\lambda_a(u^b)} + u \left((u^{-1})^b + w \right) = u(v^b + w), \quad (2)$$

then $B := S \times T$ with respect to the operations

$$(a, u) + (b, v) := (a+b, u^b + v) \quad (a, u)(b, v) := (a^u b, uv),$$

is an inverse semi-brace. We call such an inverse semi-brace B the *double semidirect product of S and T via σ and δ* .

Set $\Omega_{u,v}^a := (u^{-1})^a + v$, for all $a \in S$, $u, v \in T$, the map r_B associated to B is given by

$$r_B((a, u), (b, v)) = \left((\lambda_a(u^b), u\Omega_{u,v}^b), \left((\Omega_{u,v}^b)^{-1}u^{-1}\rho_b(a), (\Omega_{u,v}^b)^{-1}v \right) \right).$$

In the particular case of S and T semi-braces, we have the following result.

Theorem 3 Let S, T be semi-braces and B the double semidirect product of S and T via σ and δ . If r_S and r_T are solutions associated to S and T , respectively, and the following are satisfied

1. $(u^1)^a = u^a$,
2. $1^a + u = 1 + u$,

for all $a \in S$ and $u \in T$, then the map r_B associated to B is a solution.

References

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